CMPT385 Final Exam

Three Hours
Closed Book. No calculators or computers.
December 13, 2006, 2.00pm

Instructions:

Read each question before you answer it. Marks cannot be awarded if you answer some other question.

Indicate your answers clearly.

Please do not use a hard pencil.

Marks will be awarded for the style and clarity of your answer.

1. Graphics Pipeline

- 1.1. **(6 marks)** Identify three OpenGL state variables, and the commands used to change them.
- 1.2. (10 marks) Define in a sentence each of the following operations in the OpenGL Pipeline: depth calculation, lighting calculation, camera transformation, modelview calculation, scanline rendering. Then give the order that these operations are done.
- 1.3. (7 marks) Explain implementing realistic shadows is a problem in the OpenGL pipeline, and describe one simple way to implement approximate shadows in OpenGL.

2. Geometric Transformations

For the following, assume a two-dimensional graphics system. and that points are represented as column vectors. Thus, the modelview matrix is initially a 3x3 identity matrix, and calls to *glTranslate()* etc., result in a *right* multiplication of the modelview matrix by a transformation matrix.

(Assume access to a library to compute any of the usual math functions.)

- 2.1. (8 marks) The bottom row of the modelview matrix is initially (0, 0, 1). Do the values in this row ever change as a consequence of *translate*, *rotate* or *scale* operations? Show why.
- 2.2. (4 marks) An application of a *translate* operation to *any* modelview matrix representing a sequence of *translate*, *rotate* and *scale* operations affects how many entries of the modelview matrix? Show your work.
- 2.3. (4 marks) Show that any modelview matrix consisting of an arbitrary sequence of rotations and translations can be reduced to a single rotation and translation.

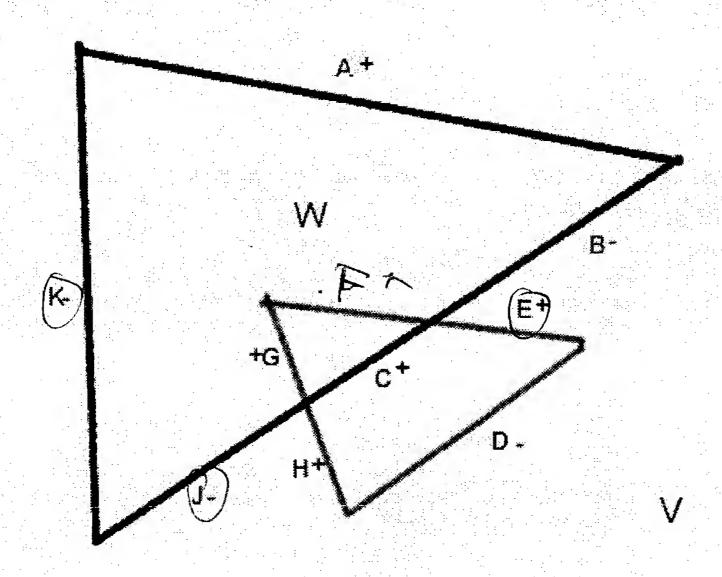
- A-Lim

3. Lighting

- 3.1. (9 marks) OpenGL uses Gouraud lighting. Summarize this lighting model and explain why it is used in OpenGL.
- 3.2. (6 marks) Briefly describe some other lighting model (radiosity, photon mapping, Phong) and discuss the feasibility of implementing these in real time using an OpenGL-like implementation.

4. Depth Calculations

- 4.1. (4 marks) Explain the z-buffer algorithm.
- 4.2. (12 marks) Consider the following scene similar to the examples used in class.



The drawing represents a bird's eye view of several rectangles arranged in two triangular shapes which intersect. The rectangles are subdivided at the intersection points, and each rectangle is labeled with a letter. Adjacent to the letter is a +/- sign indicating that the equation of that rectangle's plane is +/- in the vicinity of the letter. Show the BSP tree that would result if the following rectangles are added in the following order:

FBCGAHD

- 4.3. (8 marks) Show the order the above rectangles would be rendered from viewpoints V and W respectively.
- 4.4. (Bonus) Why didn't I include and K in the above list?

DO EITHER QUESTION 5 OR QUESTION 6

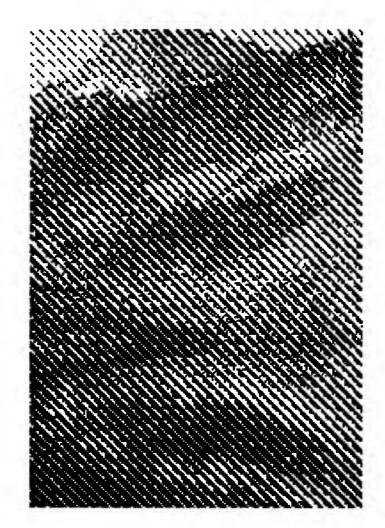
5. Halftoning (10 marks)

The following matrix could be used as a dither matrix for the halftoning assignment you did in this class. It is called a "line halftone" and creates the output shown beside the data:

```
{{36, 35, 34, 33, 32, 31}, {30, 29, 28, 27, 26, 25}, {24, 23, 22, 21, 20, 19}, {18, 17, 16, 15, 14, 13}, {12, 11, 10, 9, 8, 7}, {6, 5, 4, 3, 2, 1}};
```



The dither matrix above is very similar to the line halftone matrix used in your assignment. It is called a line matrix because there is an effect of lines crossing the image. Show how to create a line matrix that creates a diagonal line effect as follows:



DO EITHER QUESTION 5 OR QUESTION 6

6. Shaders

- 6.1. (3 marks) Explain the difference between surface shaders, bump maps, and displacement shaders.
- 6.2. (7 marks) Describe how you would use Perlin noise to write a surface shader to create a mottled surface, as on an orange. (If you can write the shader, do so. If not, sketch out an idea.

7. (12 marks) Short answer

- 7.1. Describe either particle systems or L-systems.
- 7.2. What is picking, and how does OpenGL help with this?
- 7.3. What is double buffering?
- 7.4. What is the purpose of glPushMatrix() and glPopMatrix()?
- 7.5. What is the difference between the modelview matrix and the projection matrix?
- 7.6. Distinguish between geometric and parametric continuity.

End of exam